

## **In the Specification**

Please amend paragraph 0045 beginning at page 18 of the Specification as follows.

[0045] Each transfer unit 40 includes a main body 80 which is defined having upper and lower surfaces 81 and 82. Generally, the body is defined by a steel frame covered by steel sheet metal along the upper and side surfaces. Mounting brackets 83 are provided at each of the corners extending from the upper surface of the transfer unit and connect with the mounting member 68 associated with each carriage. The mountings members may be connected utilizing conventional bolts or may be connected by welding. In order to drive the transfer units relative to the grid track system 42, the present invention provides four separate motors 90A, 90B, 90C and 90D each of which drives pinion gears ~~91 and 92~~ which are pivotally mounted as will be explained in greater detail so as to be selectively brought into meshed engagement with the spaced gear racks 66 and 67 mounted to the grid track segments 44 and 45. The motors 90A through 90D are specifically designed to provide power for moving the transfer unit 40 along the grid track segments 45 between starboard and port with respect to the container ship. Four additional motors 94A through 94D are provided for providing power to similar pinion drive gears associated therewith which are selectively moveable into engagement with the gear racks 66 and 67 secured to the grid track segments 44 so as to move the transfer unit fore and aft relative to the container ship. As the manner in which the motors 90A-D and 94A-D are used to power the drive pinions ~~91 and 92~~ is the same, only one drive assembly associated with motor 90A will be described in greater detail and is shown in Figs. 6-9. The motor 90A is fixedly mounted to a support frame 96 which

is secured to the upper surface of the transfer unit.

Please amend paragraph 0058 beginning on page 26 of the Specification as follows.

**[0058]** To further guide and control the movement of the container "C" relative to the transfer unit when in a fully raised position as illustrated in dotted line in Fig. 5, four corner guide arms 200 which are slightly flared outwardly at their lower edges 201 are provided. Each guide arm has two guide wall portions which intersect at approximately 90° with respect to one another so as to cooperatively engage the corners of the spreader beam 140 which is secured to a container as is illustrated in the drawing figure when the container is raised relative to the transfer unit as is illustrated in Fig. 4.